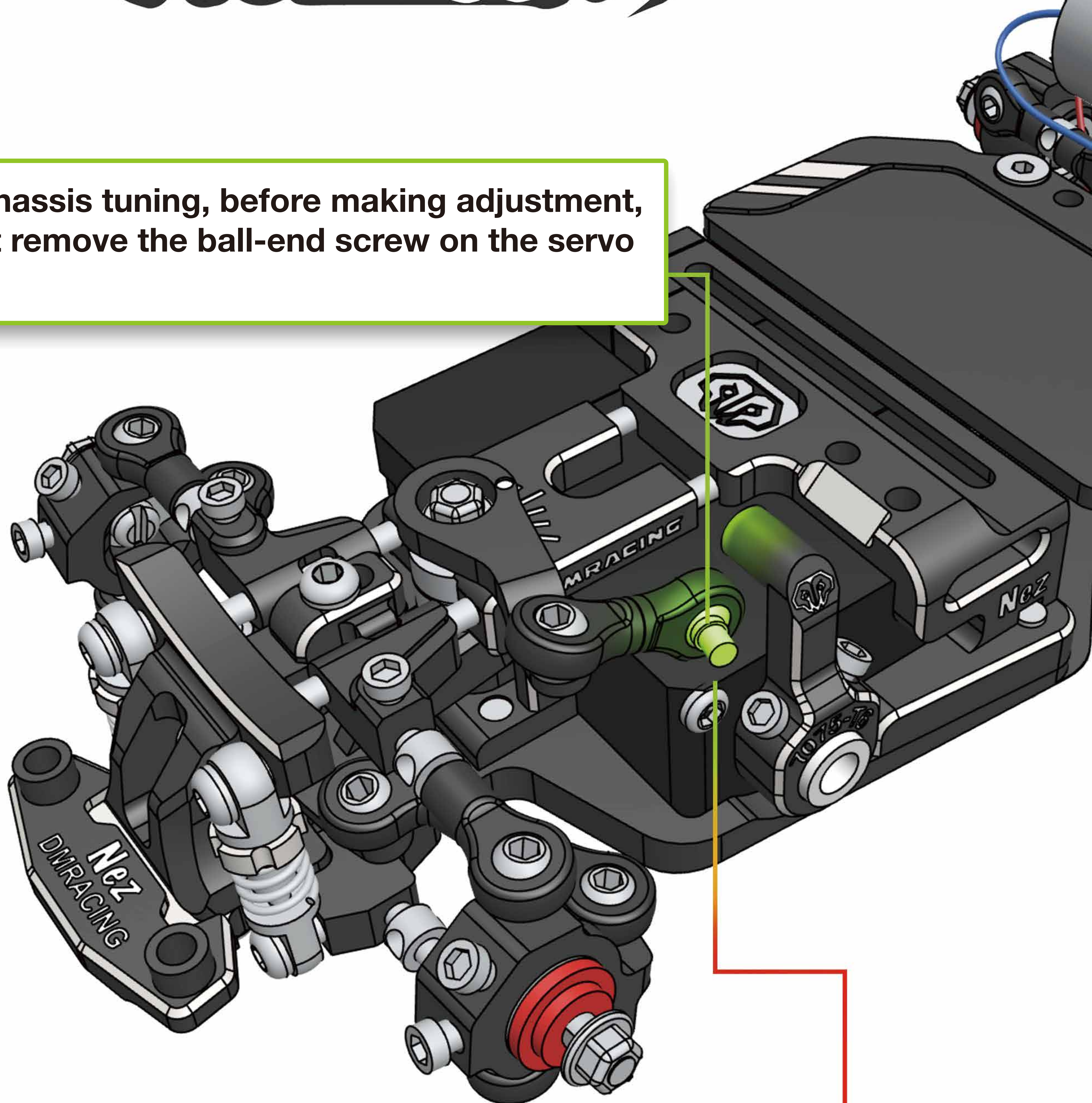


DMRACING

Nez-R

For easier chassis tuning, before making adjustment, you can first remove the ball-end screw on the servo horn.



Please note:

Before removing this ball-end screw, do not attempt to force the front wheels to steer by hand, even if the servo is powered off.

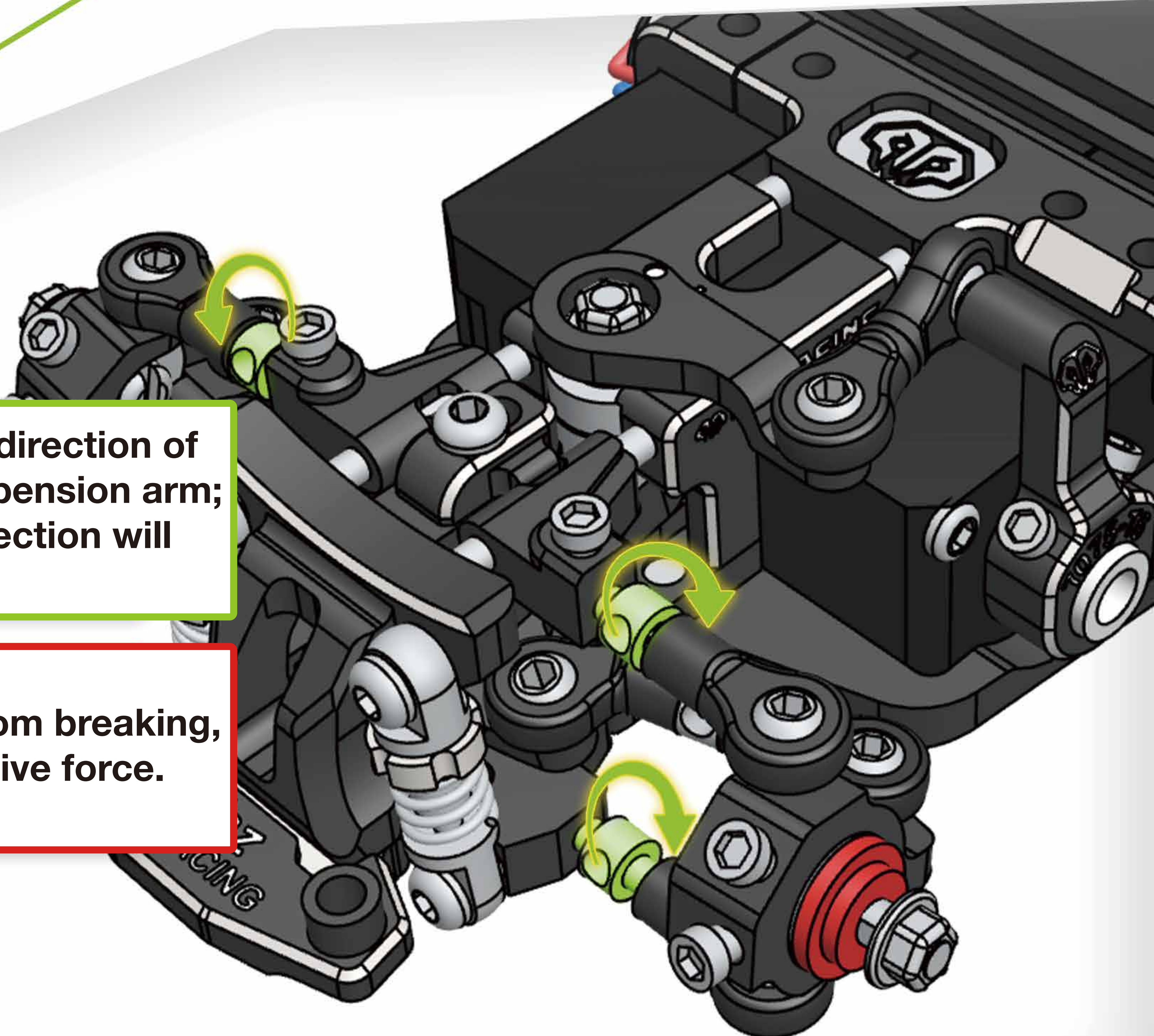
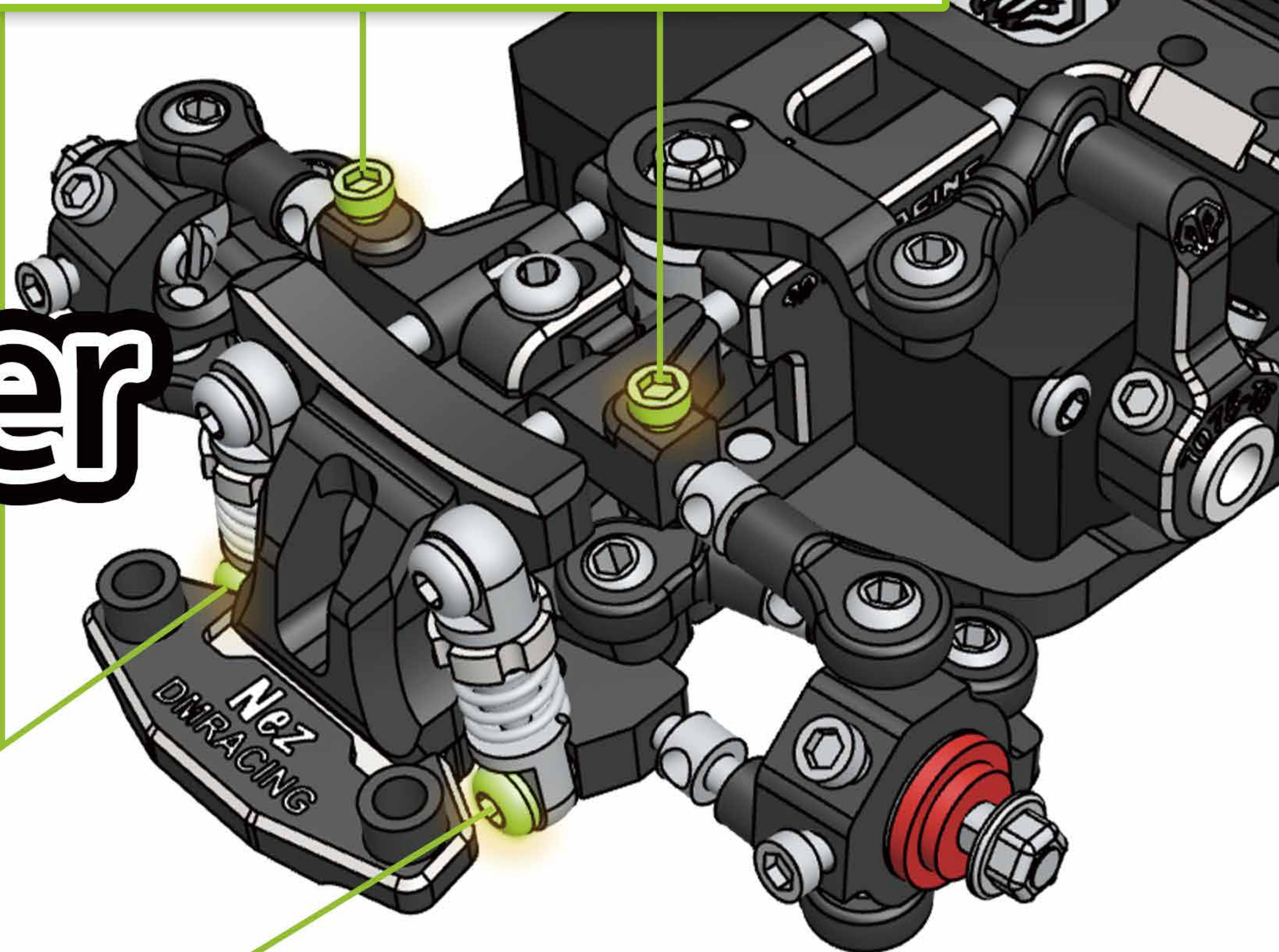
Before adjusting the upper and lower front suspension arms, loosen these four screws first, then rotate the left- and right-hand threaded turnbuckles to adjust the arm length. After the adjustment is complete, be sure to re-tighten all four screws.

Camber

Nez-Racing

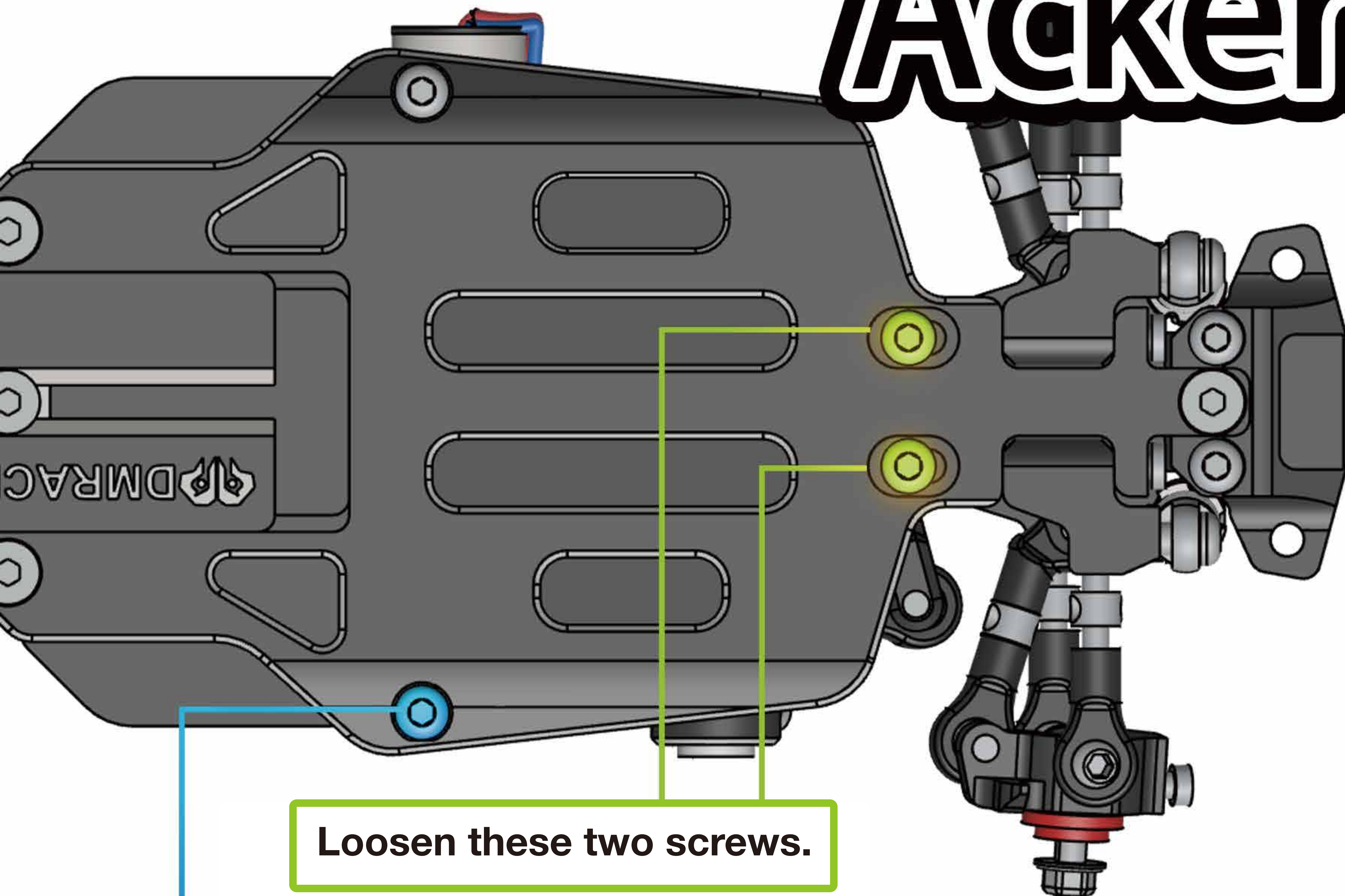
Rotate the turnbuckle in the direction of the arrow to shorten the suspension arm; rotating it in the opposite direction will lengthen it.

To prevent the turnbuckle from breaking, do not rotate it using excessive force.



Ackerman

Nez-R

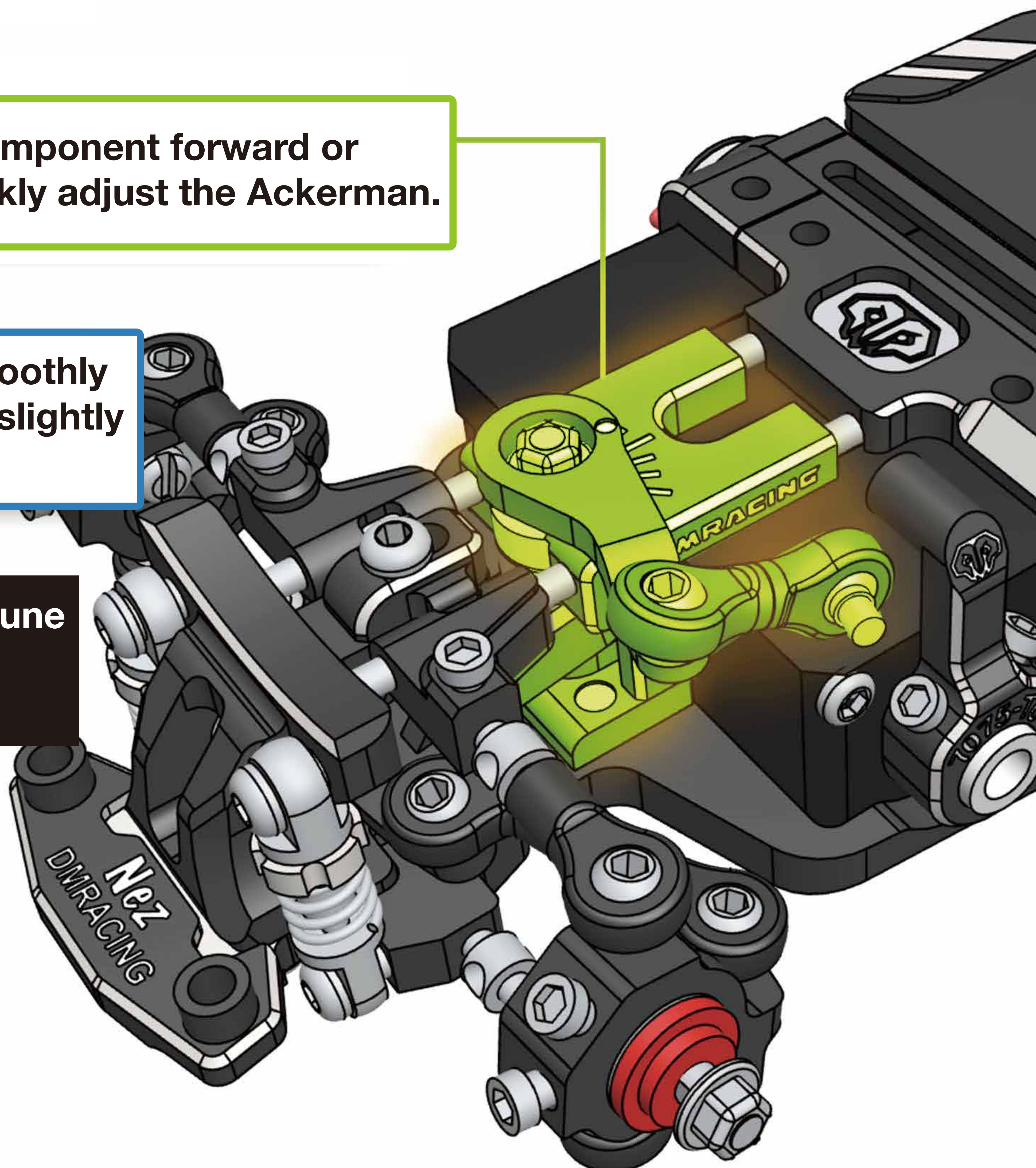


Loosen these two screws.

Then slide this component forward or backward to quickly adjust the Ackerman.

If the component does not slide smoothly forward or backward, you can also slightly loosen this screw.

After adjusting the Ackerman, fine-tune the servo neutral position using the transmitter.



1

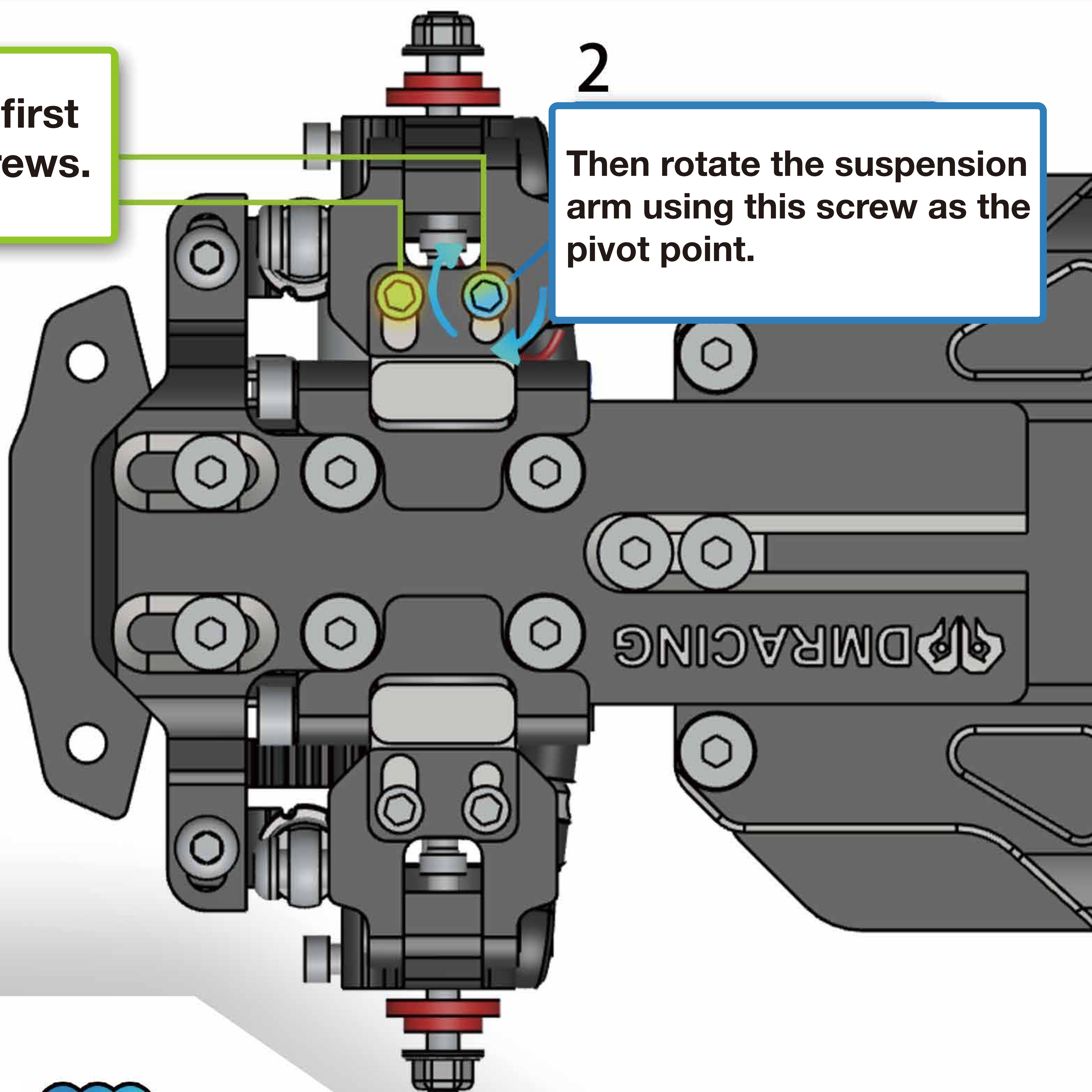
To adjust the rear toe angle, first slightly loosen these two screws.

2

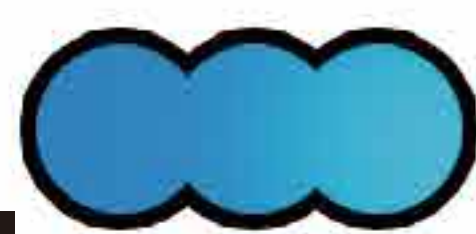
Then rotate the suspension arm using this screw as the pivot point.

Toe

Nez-R



The rear lower suspension arm length is adjustable in 3 positions.

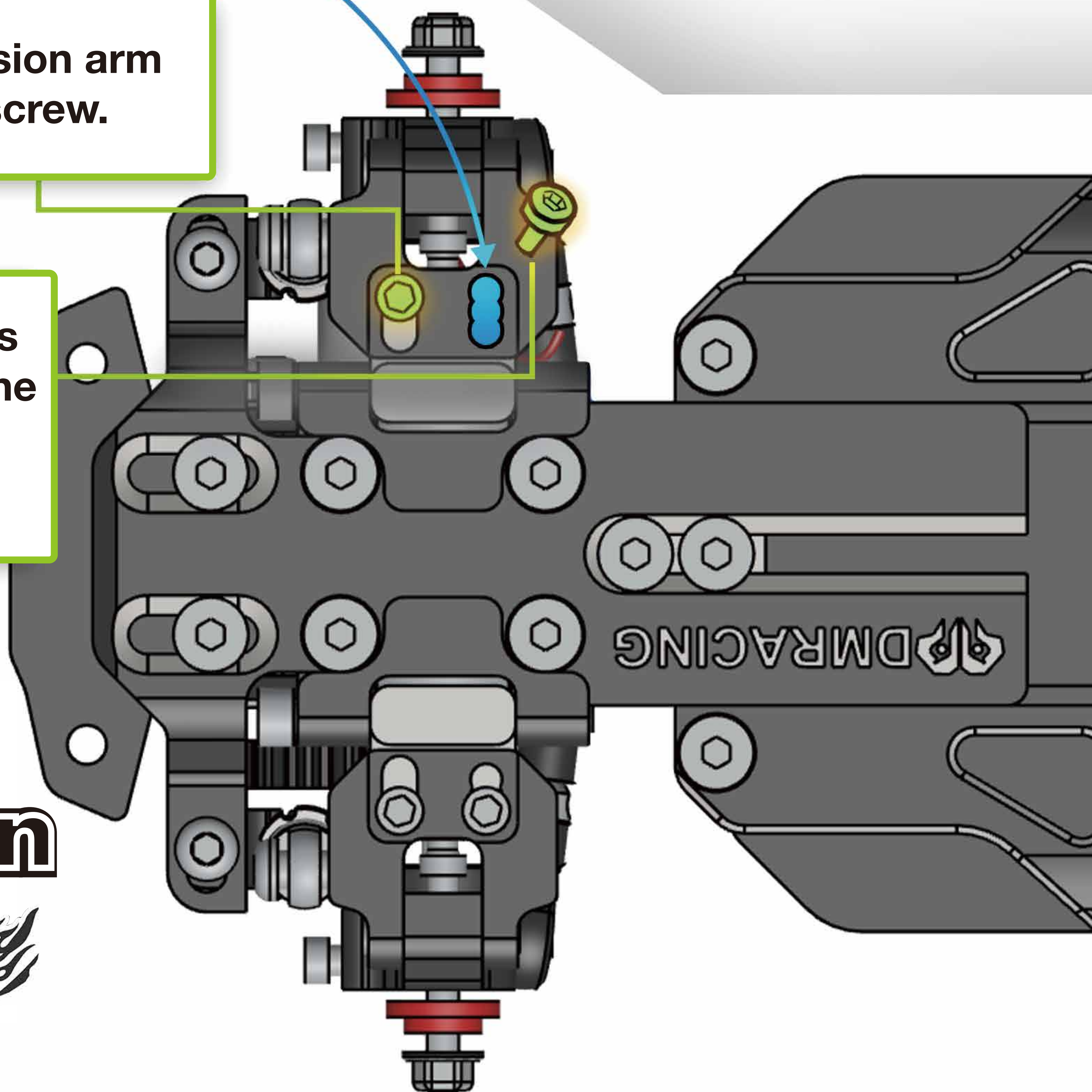


1

When adjusting the suspension arm length, slightly loosen this screw.

2

Then temporarily remove this screw, and reinstall it after the suspension arm length has been adjusted.

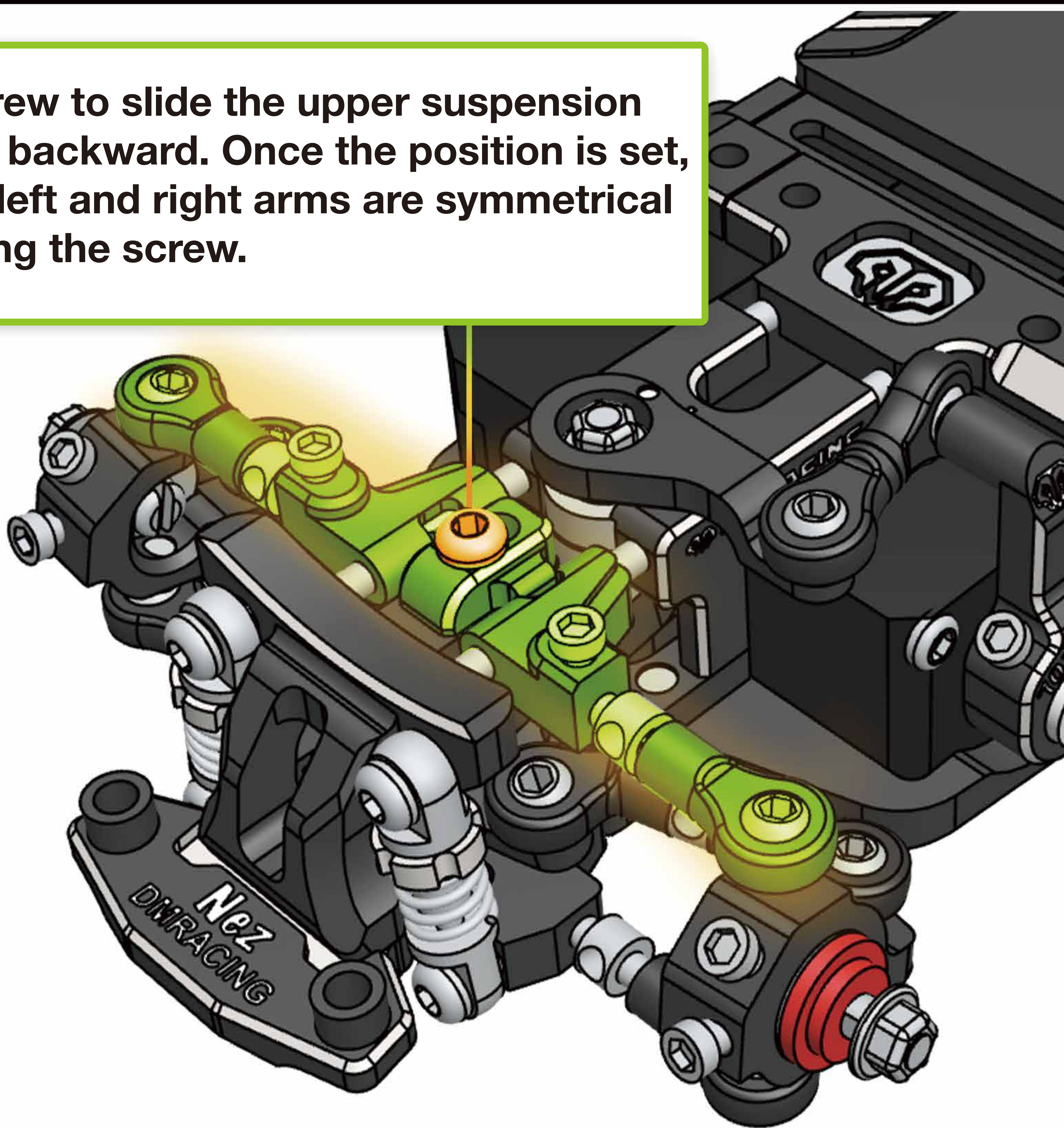


Lower Suspension Arm

Nez-R

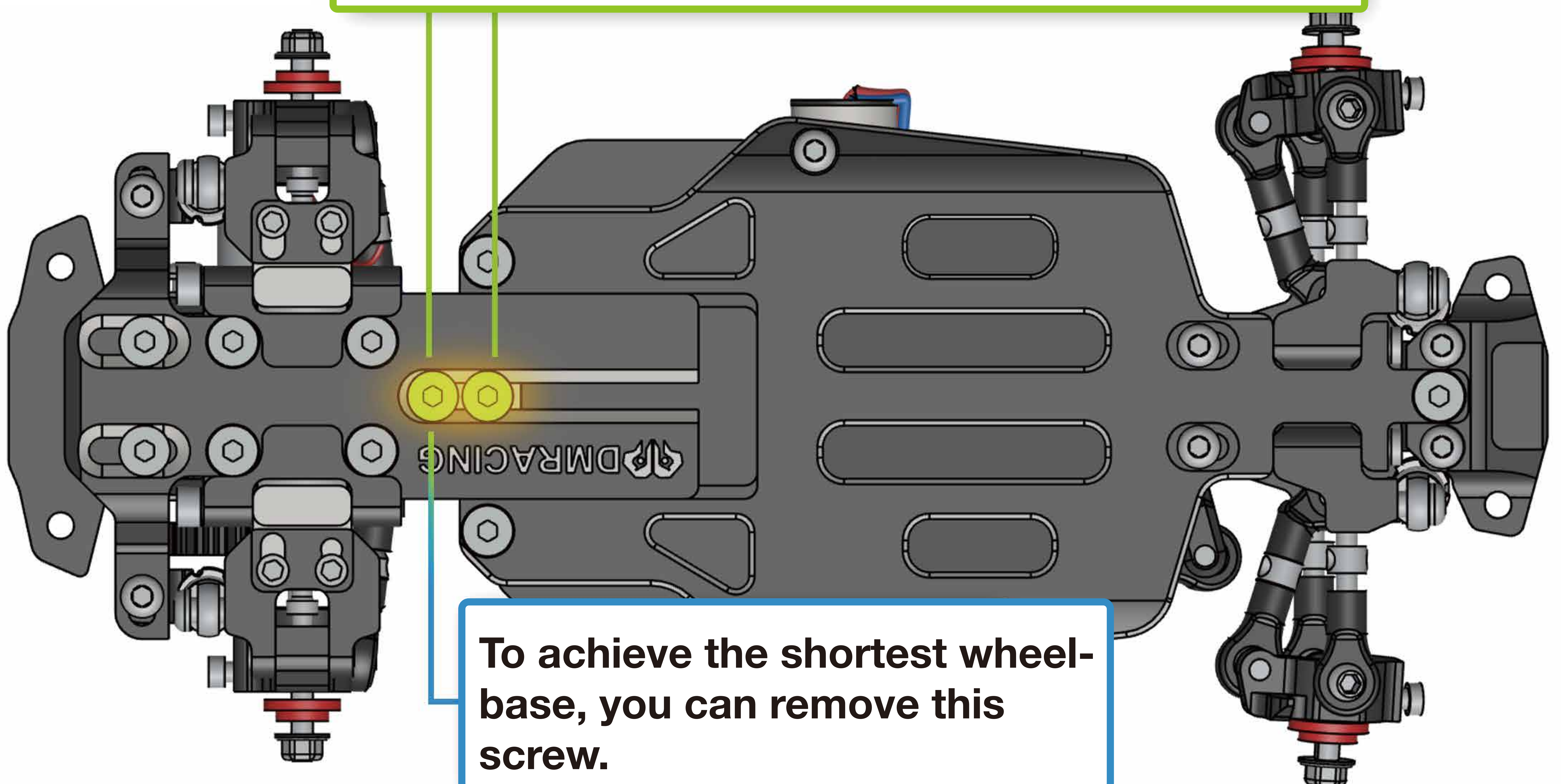
Loosen this screw to slide the upper suspension arm forward or backward. Once the position is set, check that the left and right arms are symmetrical before tightening the screw.

Nez-K Caster

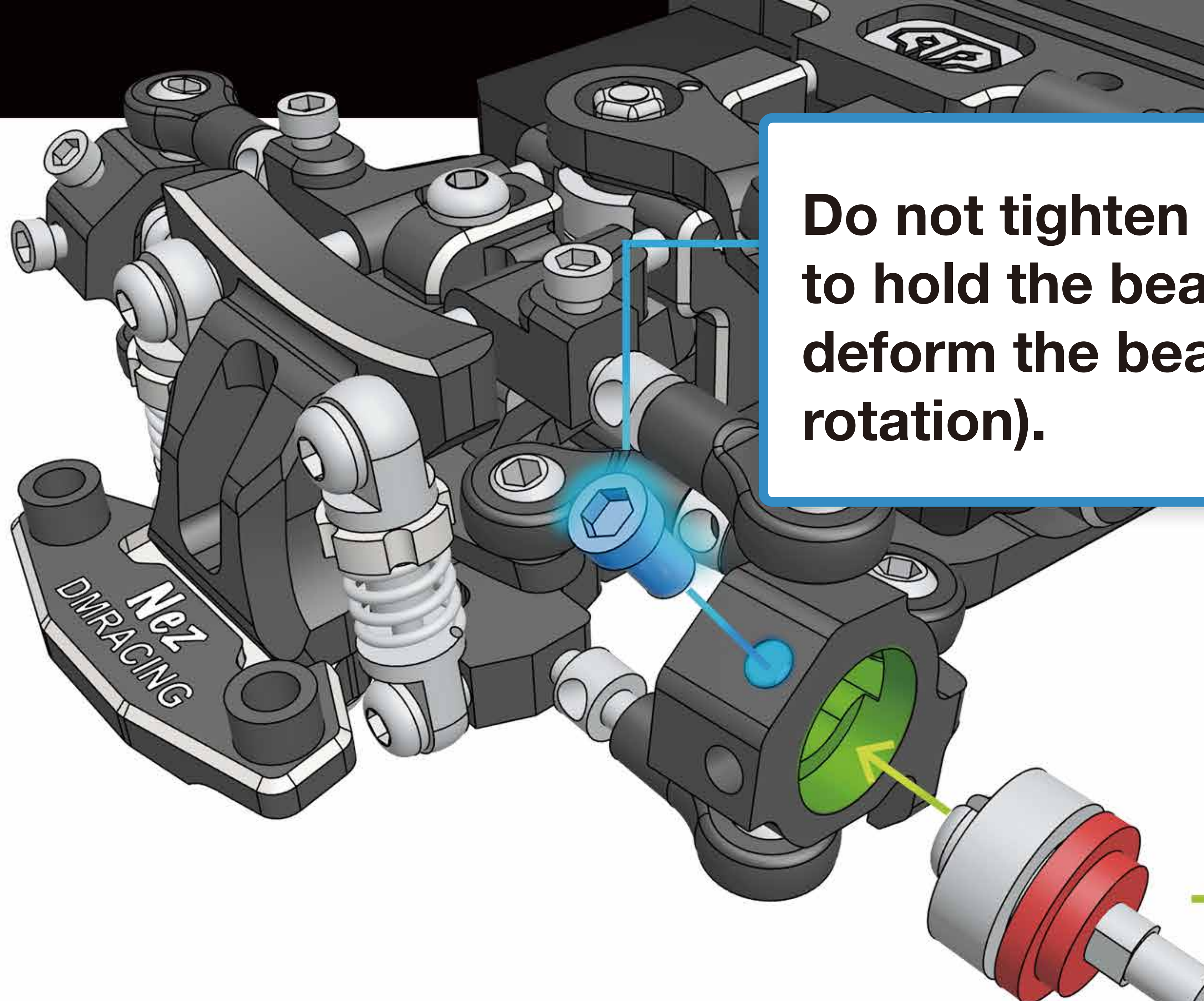


Wheelbase Nez-K

Loosen this screw to adjust the wheelbase length.

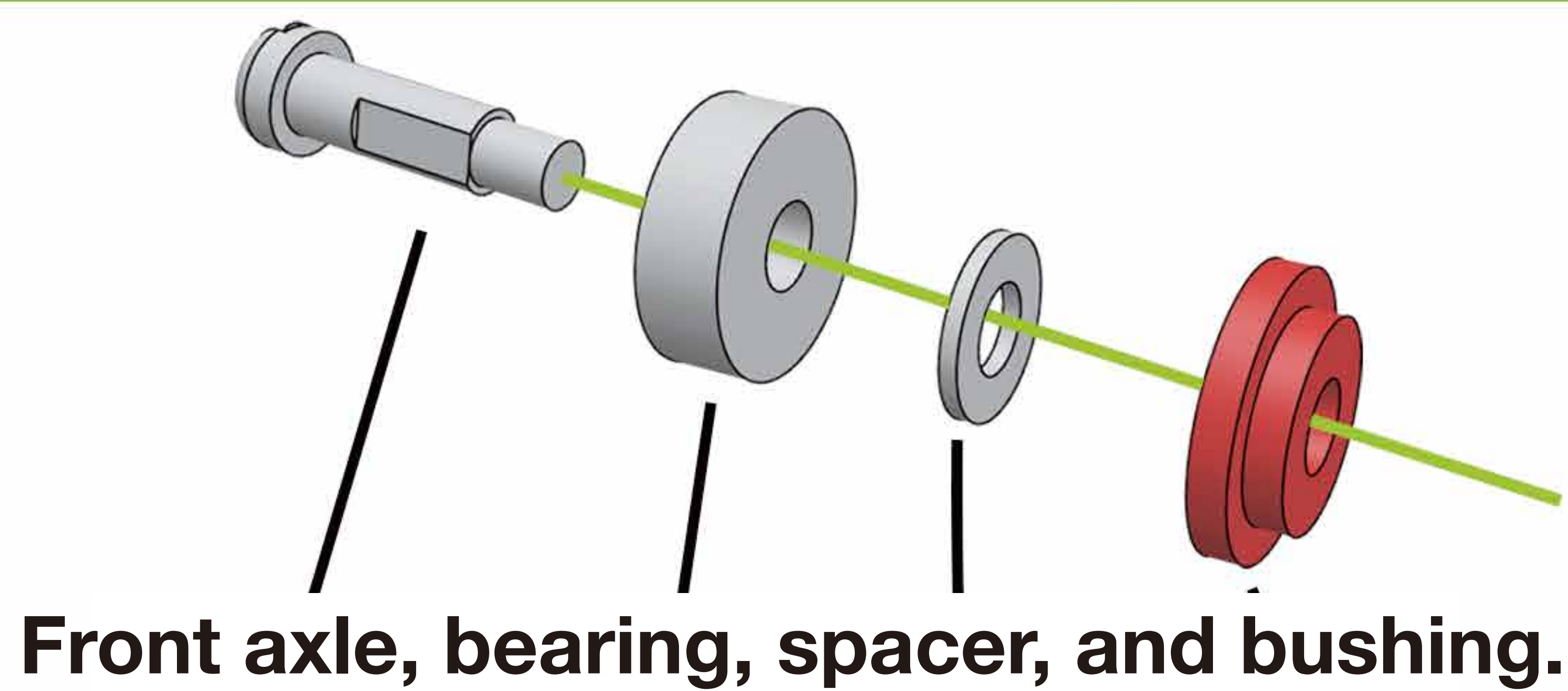


To achieve the shortest wheelbase, you can remove this screw.



Do not tighten this screw too much—just enough to hold the bearing in place (over-tightening can deform the bearing and affect the front wheel rotation).

Front Axle

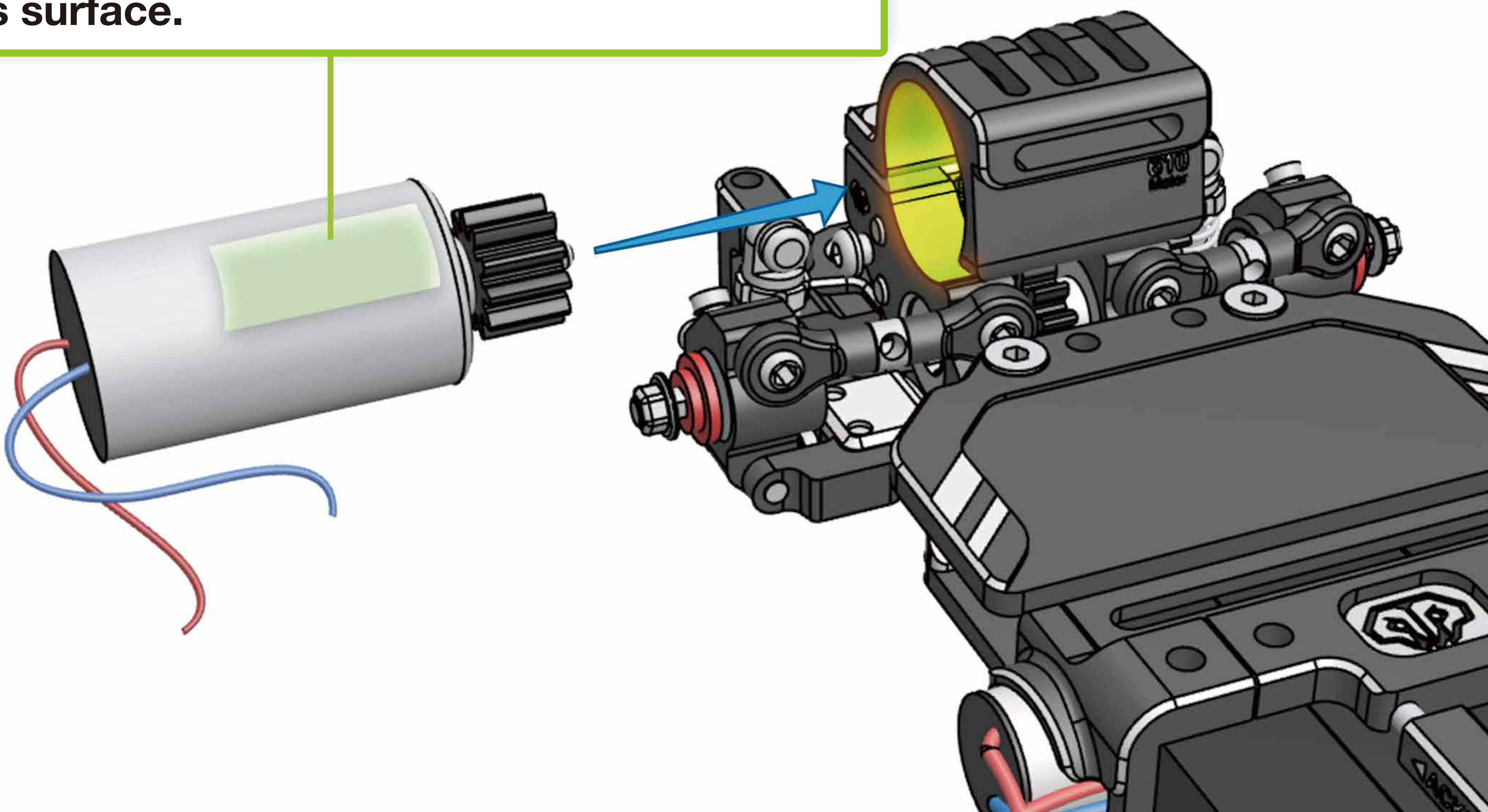


Motor



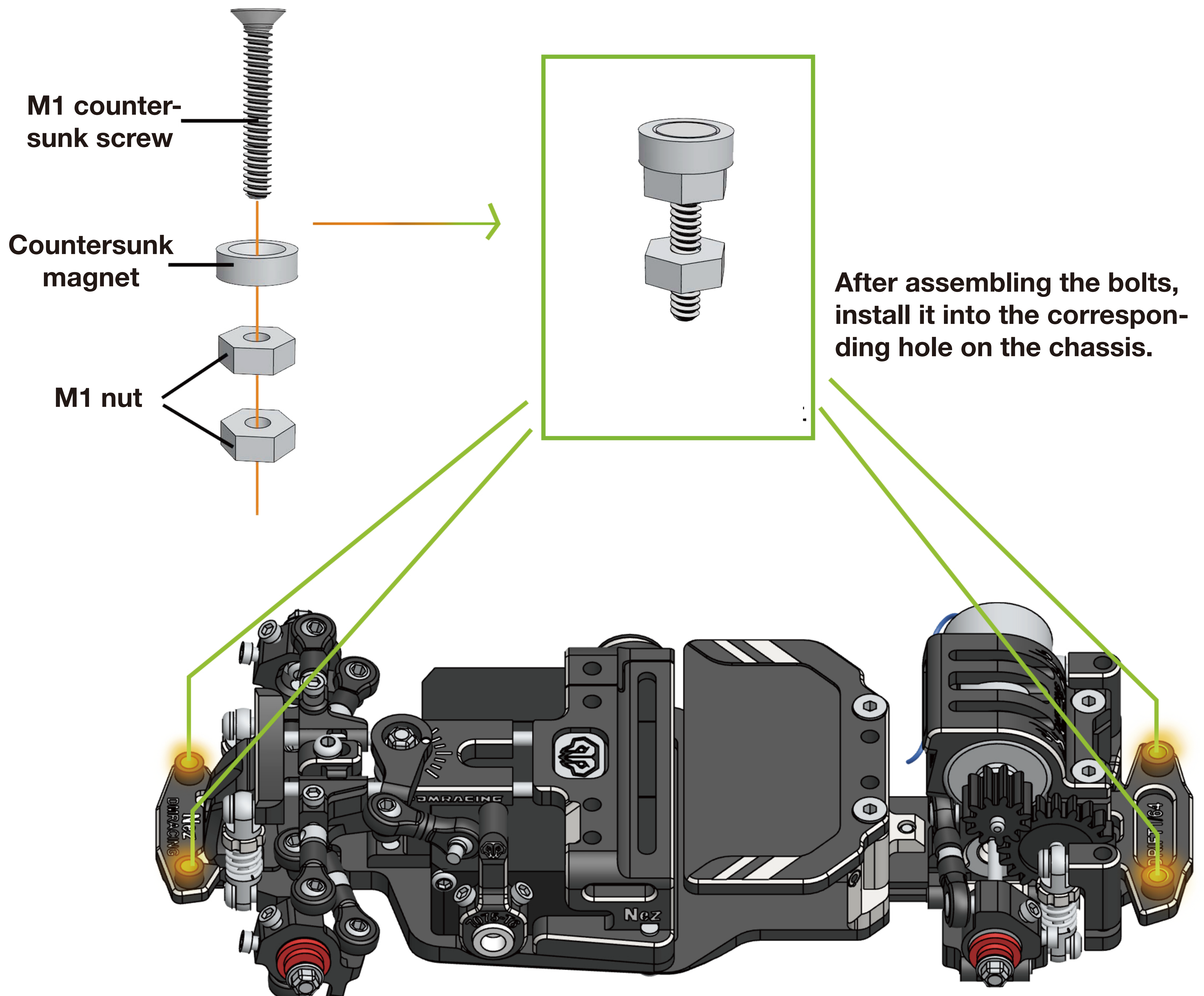
After soldering the motor to the ESC, insert the motor into the motor mount.

If the motor is too loose, you can apply a piece of tape to its surface.

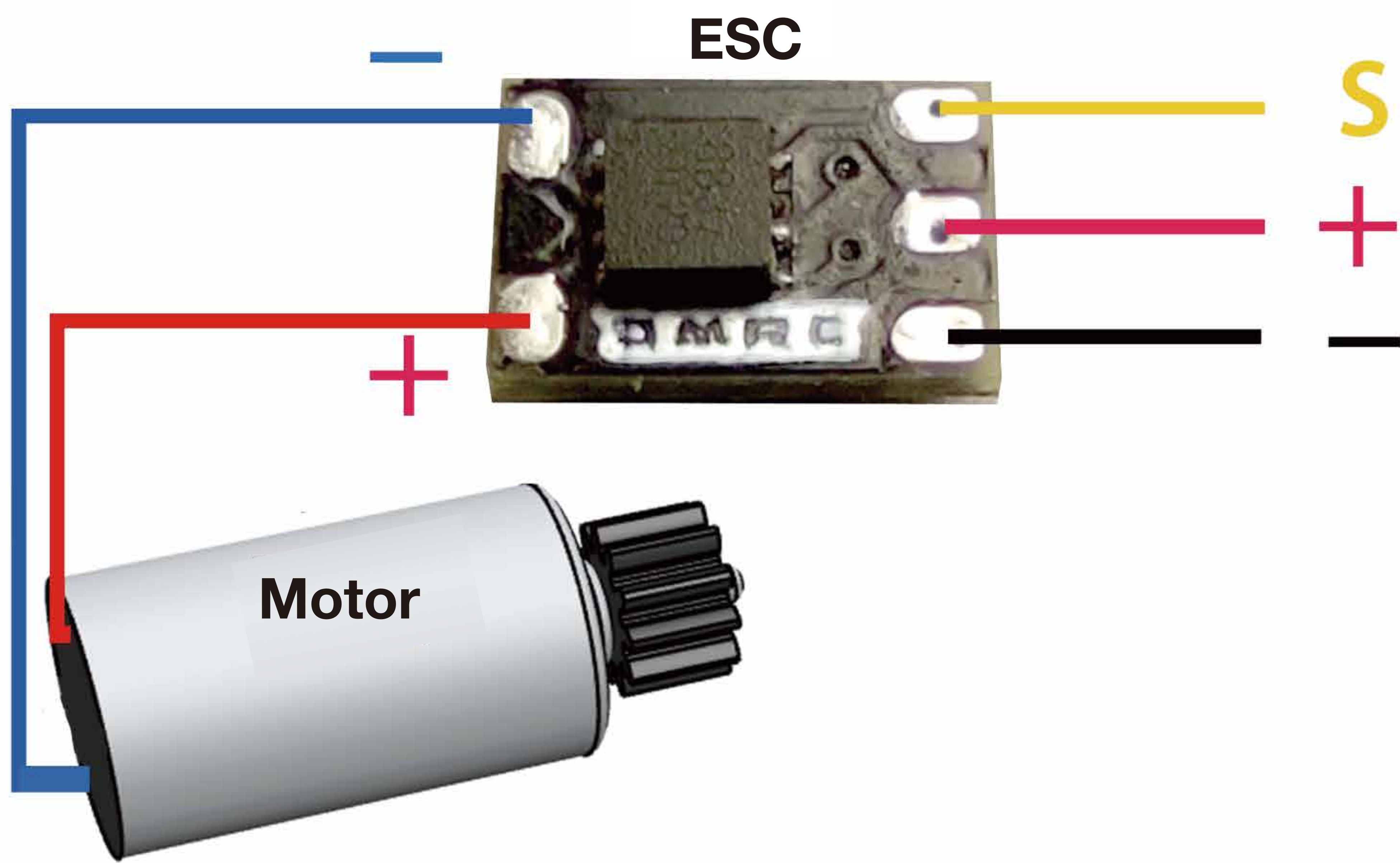


Shell Bolts Installation

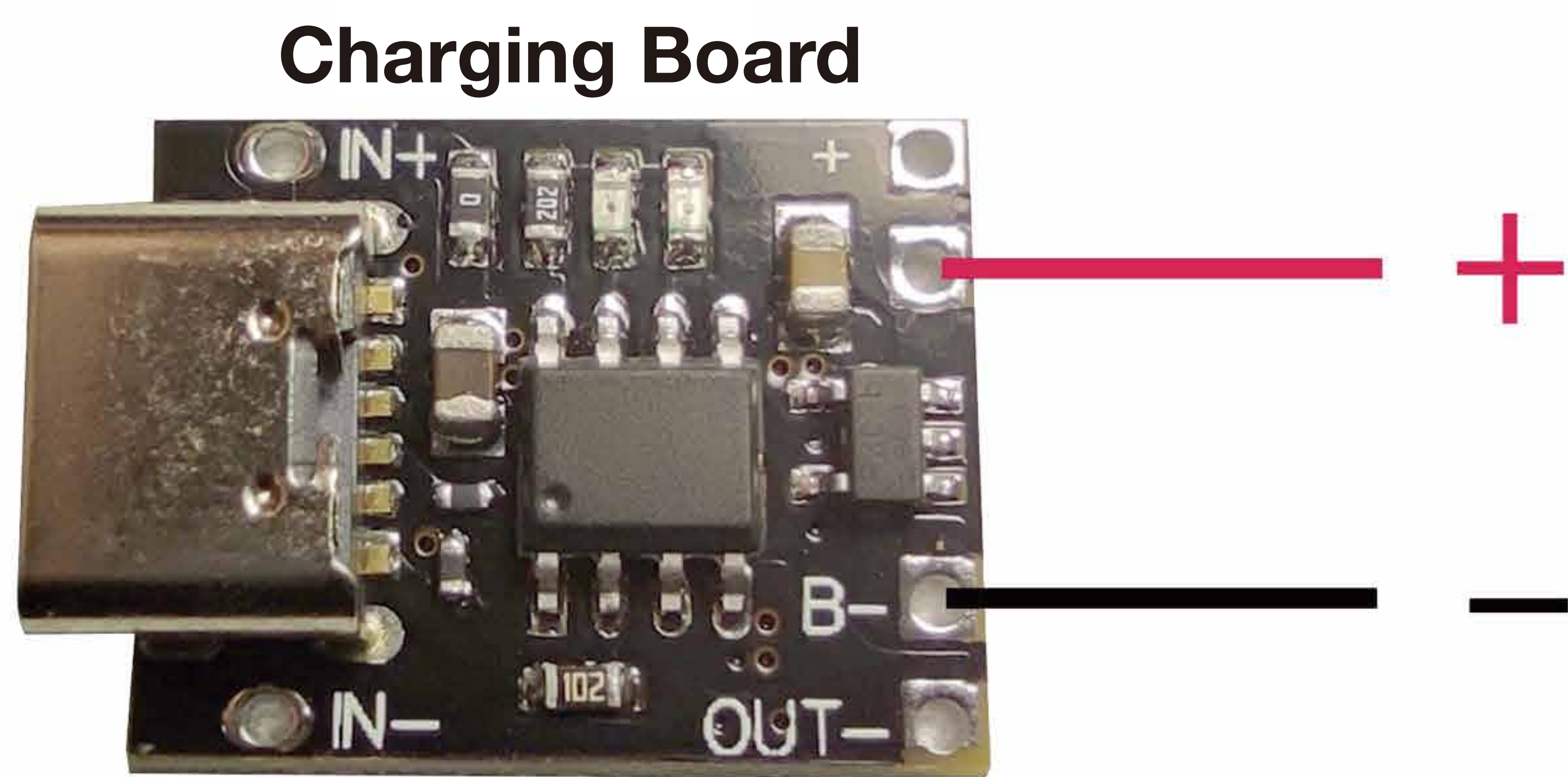
Nez-K



1 ESC wiring sequence for soldering.



2 Wiring sequence for the charging board.



3 Receiver Connectors

